

Veyron3 HD

FPV Racing Drone

Manual



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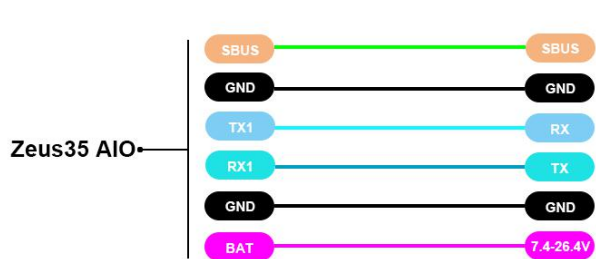
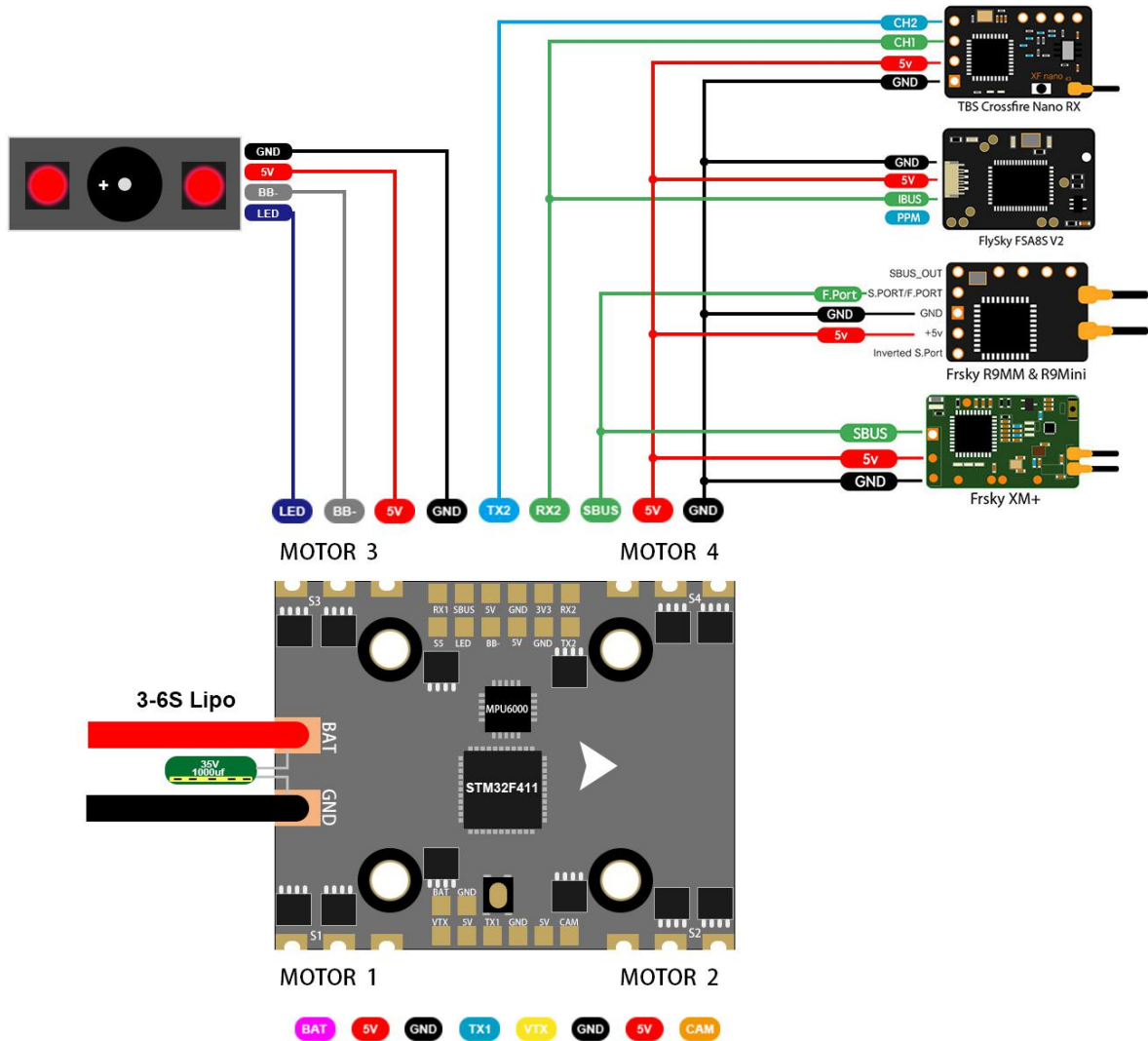
Package Included

Veyron3 HD FPV Racing Drone *1	
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1.Product Specifications

Product parameters	
Model	Veyron3 HD FPV Racing Drone
Weight	267.0g(BNF) 266.0g (PNP)
Frame Kit	Veyron3 Frame Kit
Flight Controller	Zeus35 AIO
ESC	35A 4in1
VTX	CaddxVista
Camera	DJIFPVCamera
Motor	FD1408 kv2400 (6S) KV3600 (4S)
Support receiver	SBUS .DSMX.i.BUS
Input Voltage	3-6S Lipo
Size	205X188mm

2. Interface Description



3. Check the flight control drive

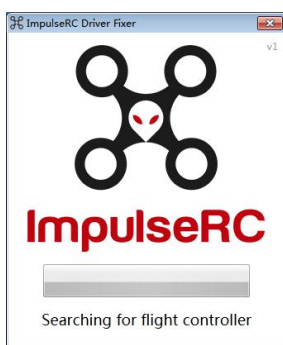
1. Long Press BOOT buttons.connect USB.The system automatically install the driver



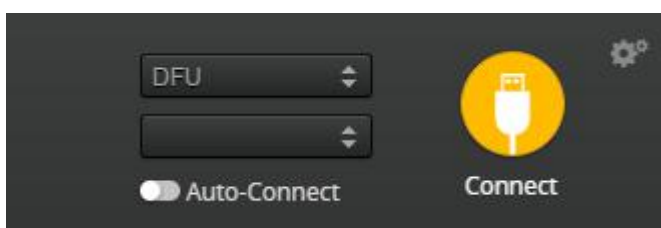
2.Driver cannot be installed, please download ImpulseRC_Driver_Fixer



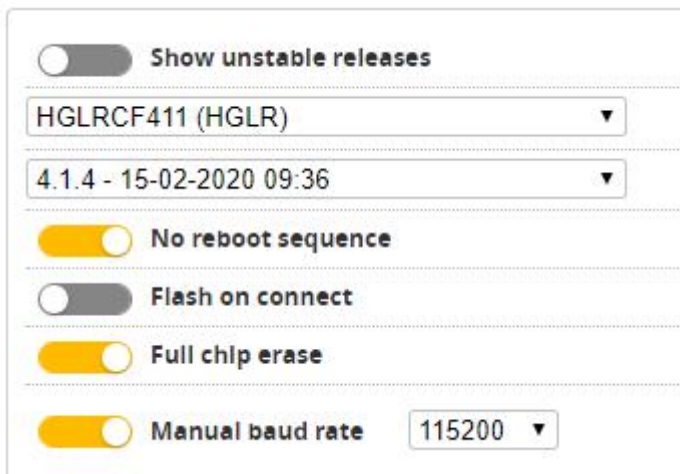
3.Double-click on the run(Plug in the flight controller to automatically install the driver)








4.open betafight configurator , enter DFU mode

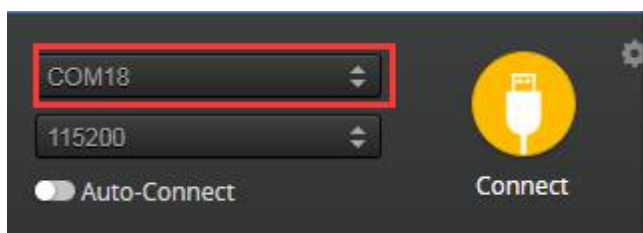


5. Click  Select firmware version




6. Click  Load firmware.  Waiting for completion  It will be prompted upon completion. 

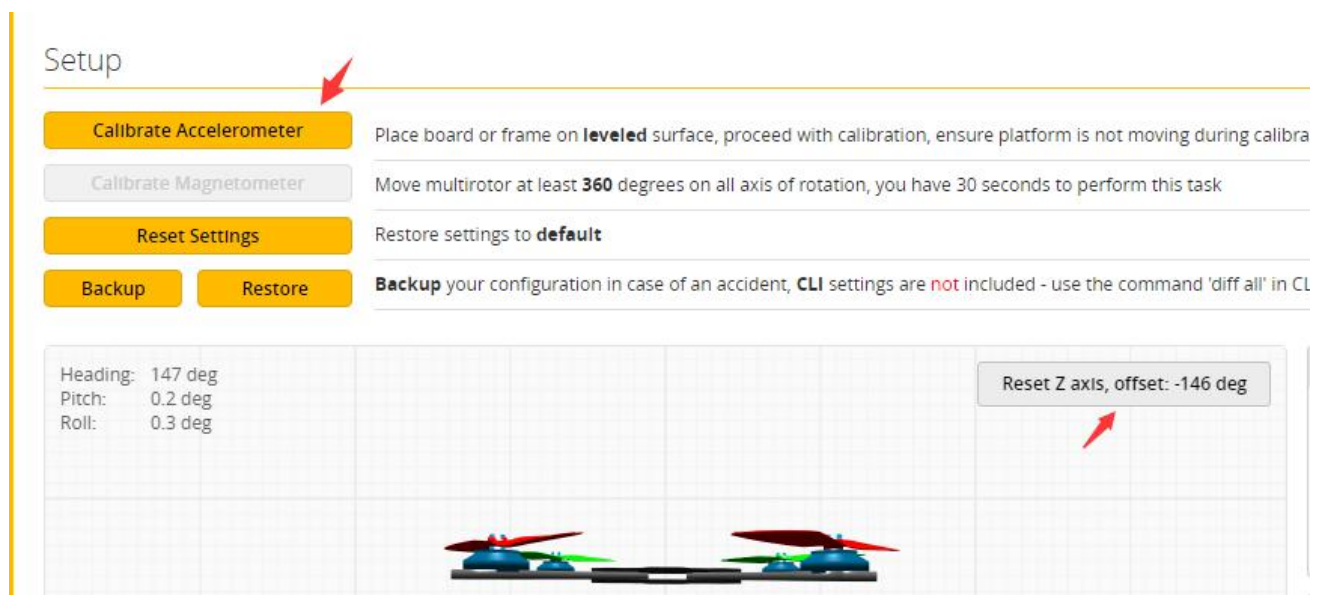
7. open betafight configurator  . Controller plugged into the computer. Betaflight Automatically assigned port, click “Connect”
Enter setup interface (Different computer COM)



4. Calibration accelerometer

1. Put the aircraft horizontal and click “Reset Z axis”

Click again 



The screenshot shows a web interface for calibrating an accelerometer. The 'Setup' section contains several buttons: 'Calibrate Accelerometer' (highlighted with a red arrow), 'Calibrate Magnetometer', 'Reset Settings', 'Backup', and 'Restore'. Below these buttons, there are instructions for each step. The 'Calibrate Accelerometer' step instructs the user to place the board on a leveled surface. The 'Reset Settings' step instructs the user to restore settings to default. The 'Backup' and 'Restore' steps instruct the user to backup their configuration in case of an accident, noting that CLI settings are not included. Below the instructions, there is a status panel showing 'Heading: 147 deg', 'Pitch: 0.2 deg', and 'Roll: 0.3 deg'. To the right of the status panel, there is a button labeled 'Reset Z axis, offset: -146 deg' with a red arrow pointing to it. At the bottom of the interface, there is a 3D model of a multirotor aircraft.

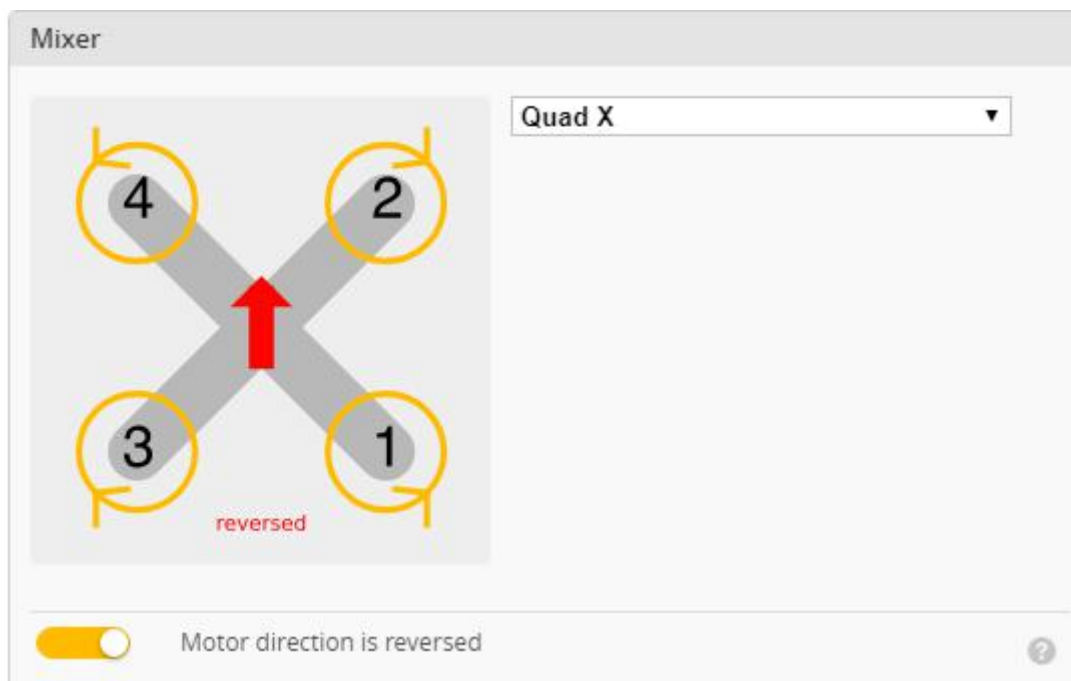
5. URAT serial port use


URAT1 uses VTX image transmission

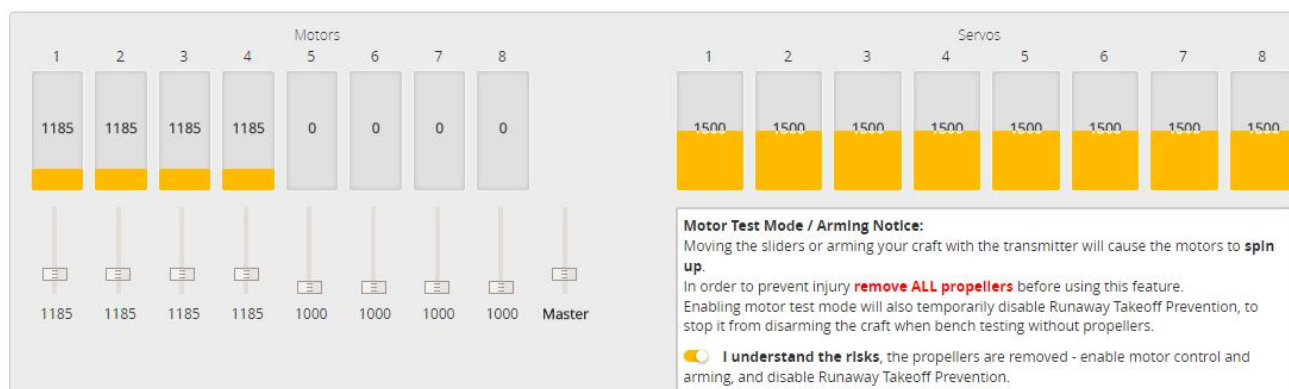
UART2 uses receiver telemetry

6. Select aircraft model

1. Click  Configuration Select model

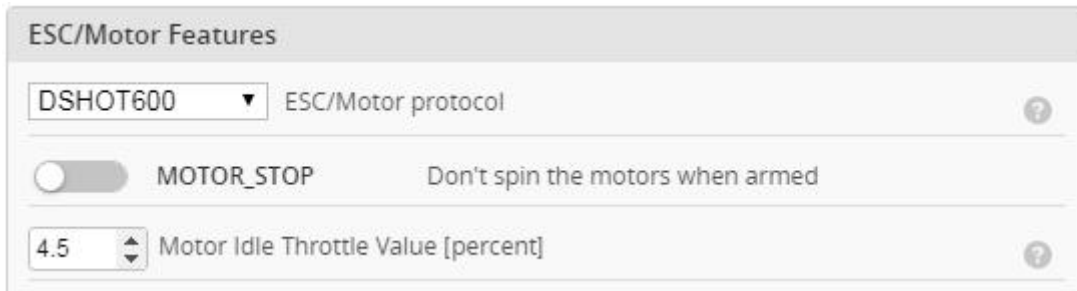


2. Click  Motors Click “**I understand the risks**” Push Master to check motor steering “**Master**” Steering can be changed at [BLHeliSuite](#)



7. Choose ESC protocol

1. Choose the right ESC protocol, the optional universal protocol DSHOT600.



ESC/Motor Features

DSHOT600 ESC/Motor protocol

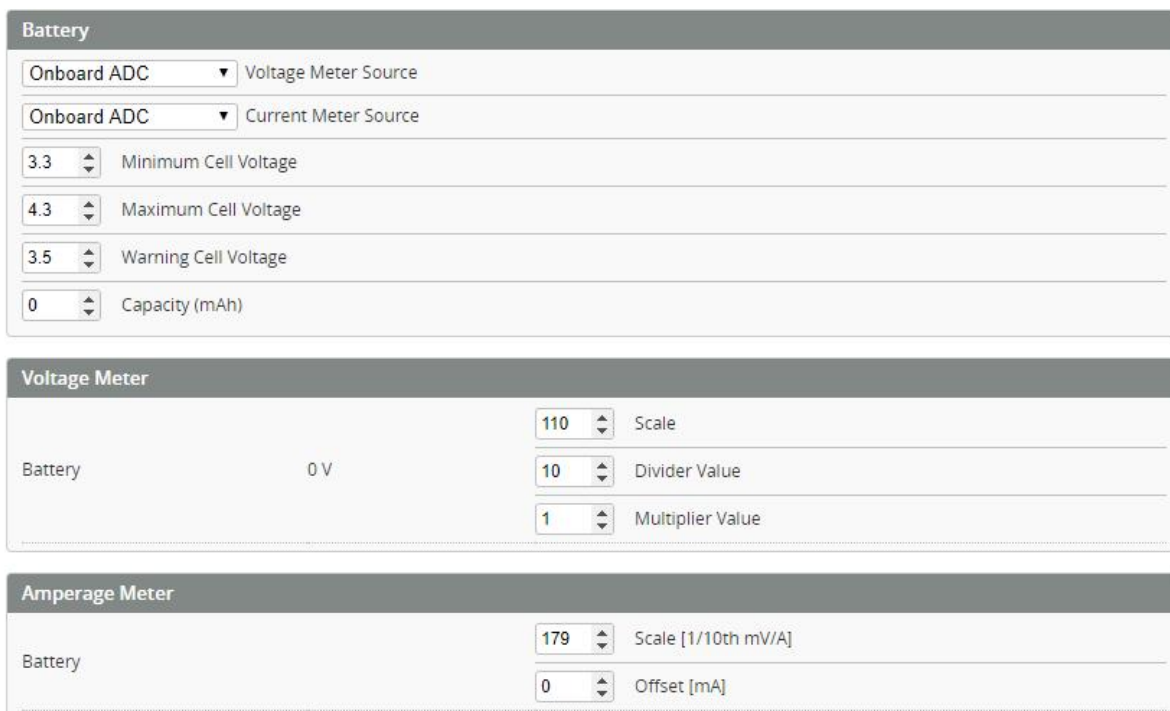
MOTOR_STOP Don't spin the motors when armed

4.5 Motor Idle Throttle Value [percent]

8. Voltage parameters setting

1. Click **Power & Battery** Setting parameters

Power & Battery



Battery

Onboard ADC Voltage Meter Source

Onboard ADC Current Meter Source

3.3 Minimum Cell Voltage

4.3 Maximum Cell Voltage

3.5 Warning Cell Voltage

0 Capacity (mAh)

Voltage Meter

Battery 0 V

110 Scale

10 Divider Value

1 Multiplier Value

Amperage Meter

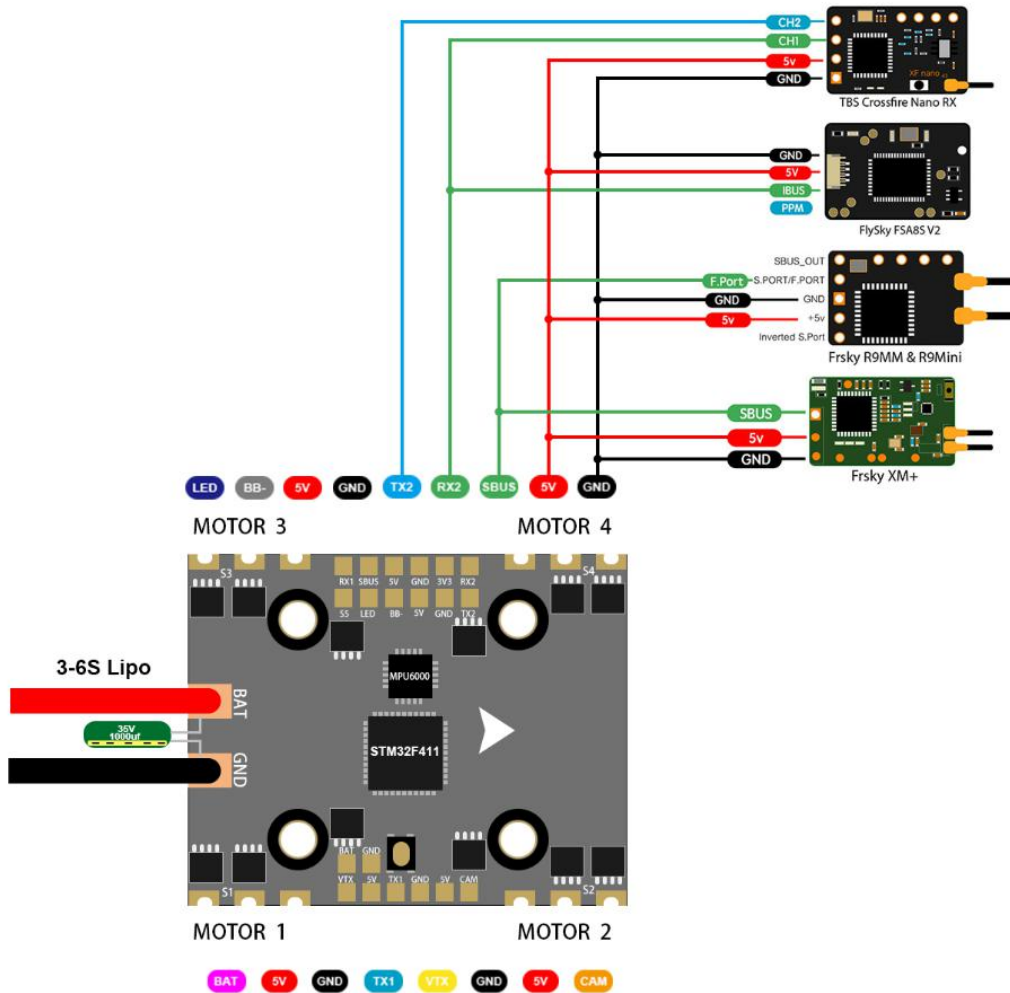
Battery

179 Scale [1/10th mV/A]

0 Offset [mA]

9. Setting up the receiver

1. Receiver connection diagram



2. Click Ports have found "UART2" Open (SBus) the receiver serial port

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	VTX (IRC Tran) AUTO
UART2	<input type="checkbox"/> 115200	<input checked="" type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO

3. Open (i.BUS/DSMX) receiver serial port

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	VTX (IRC Tran) AUTO
UART2	<input type="checkbox"/> 115200	<input checked="" type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO

4. Set the **SBUS** receiver

Receiver

Serial-based receiver (SPEKSAT, S ▼) Receiver Mode

Note: Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX_SERIAL feature.

SBUS Serial Receiver Provider

5. Set the **i.BUS** receiver

Receiver

Serial-based receiver (SPEKSAT, S ▼) Receiver Mode

Note: Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX_SERIAL feature.

IBUS Serial Receiver Provider

6. Set the **DSMX** receiver

Receiver

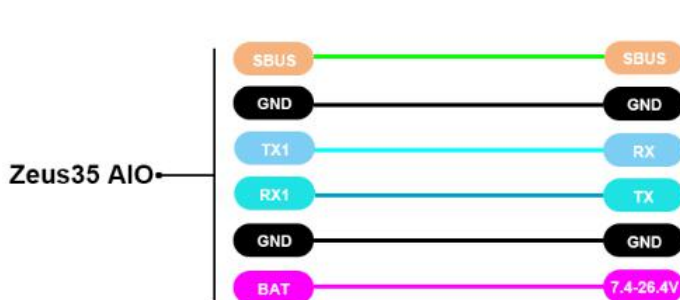
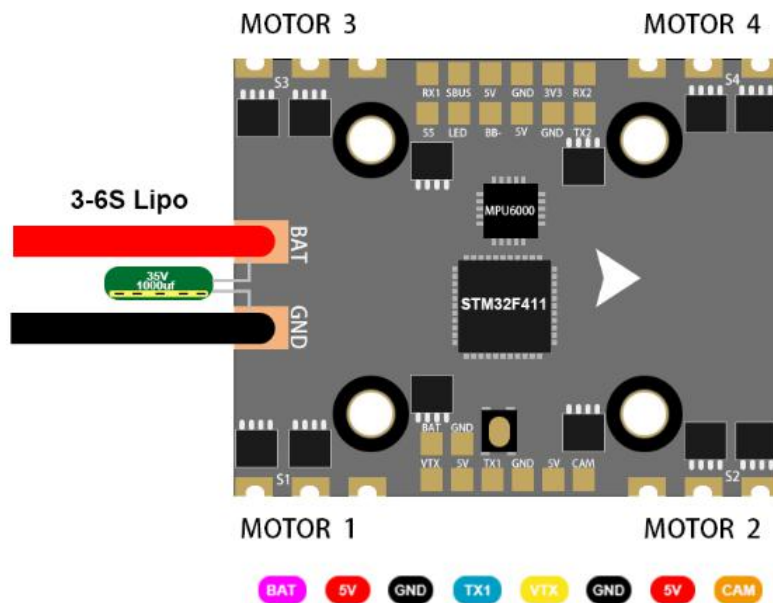
Serial-based receiver (SPEKSAT, S ▼) Receiver Mode

Note: Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX_SERIAL feature.

SPEKTRUM2048 Serial Receiver Provider

10.VTX serial port use. VTX uses OSD smart audio

1.VTX connection diagram

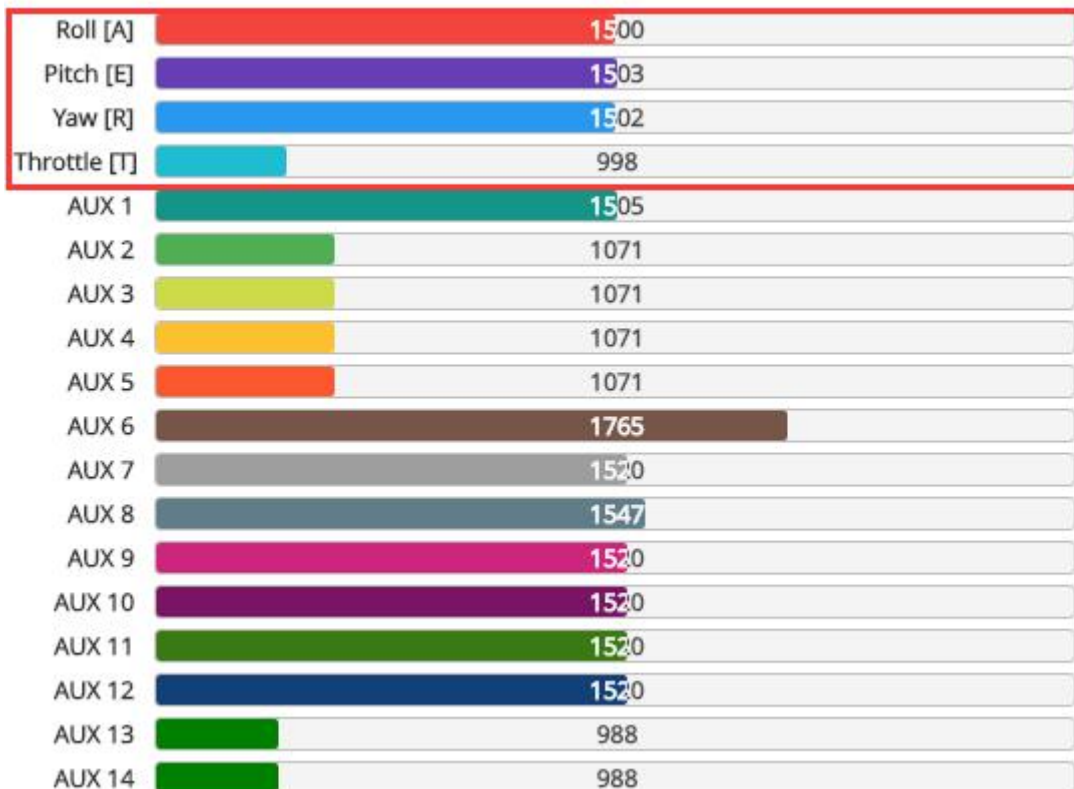


2.VTX serial port opens. The protocol is selected according to its own VTX protocol.


Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input checked="" type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	<input type="checkbox"/> 115200	<input checked="" type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO

11. Check receiver signal

1. Click  Receiver Check the remote control output signal



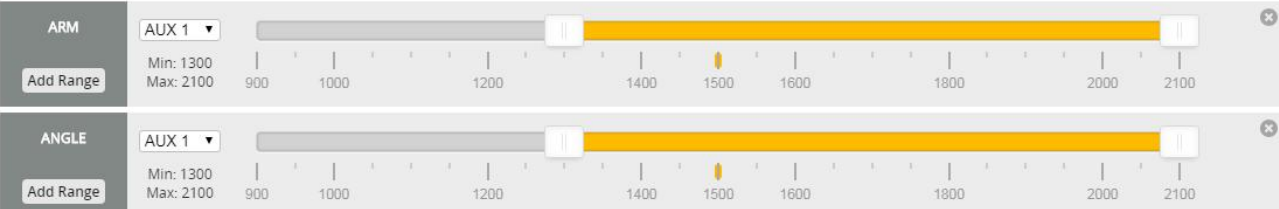
12. Select flight mode startup mode

1. Click  Modes set up the function of remote control switch across the channel (below are for reference only)

Modes WIKI

Use ranges to define the switches on your transmitter and corresponding mode assignments. A receiver channel that gives a reading between a range min/max will activate the mode. Remember to save your settings using the Save button.
 Show/hide unused modes

Mode	Channel	Min	Max
ARM	AUX 1	1300	2100
ANGLE	AUX 1	1300	2100

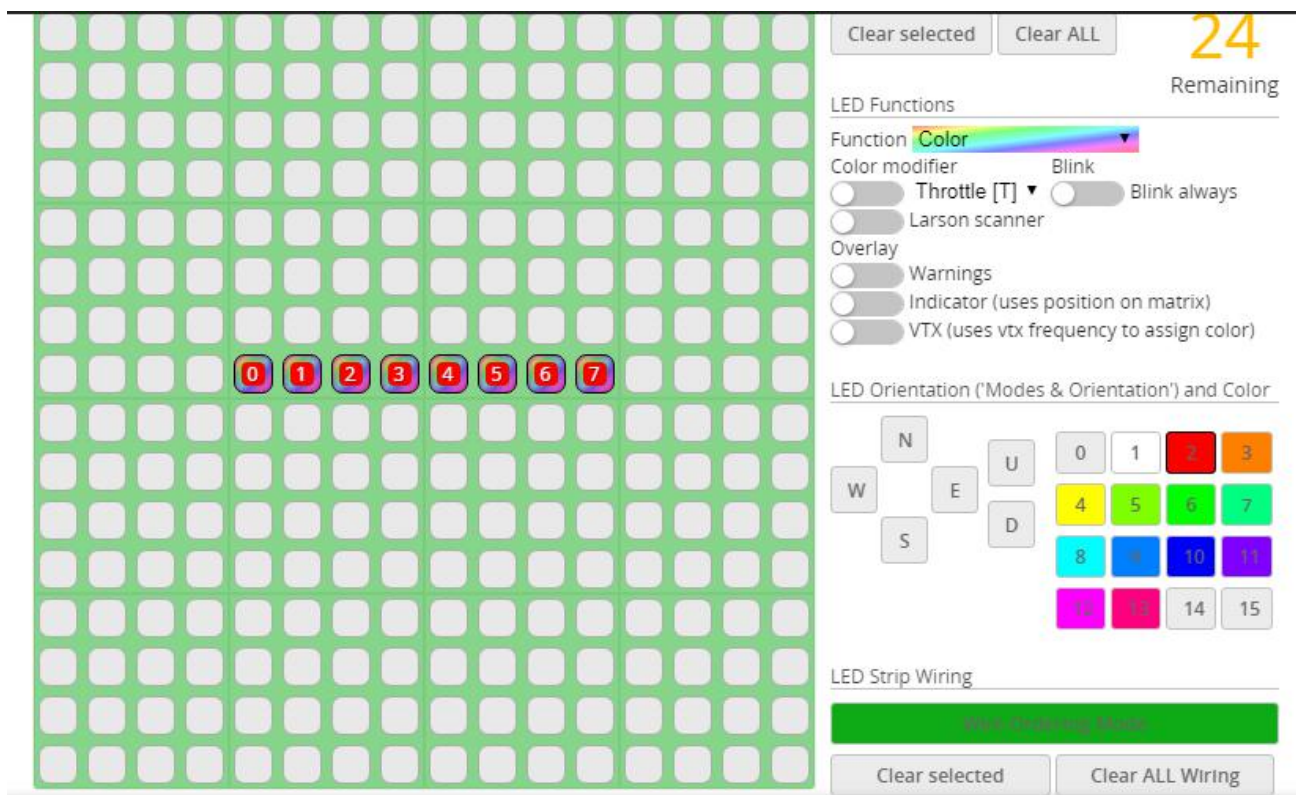


13. LED settings

1. Click  Configuration Turn on LED support

LED_STRIP Multi-color RGB LED strip support

2. Click **LED Strip**. Click **Wire Ordering Mode** set according to need



14. Troubleshooting

Warning:

Please read the cautions as follows, otherwise stability of your flight controller cannot be ensured, your flight controller will even get damaged.

- Keep focus on the polarity. Check carefully before power supply.
- Cut off the power when you connect, plug and pull anything.
- The refresh rate of PID and Gyroscope is up to 8K/8K.

after sales question:

1. After receiving the goods, it is found that the product can not be used normally. If the return to the factory is a quality problem, the repair service will be provided free of charge.
2. If the product is damaged due to improper operation, the repair service may be provided under the condition that the inspection can be repaired.
3. For domestic customers, please contact the after-sales service personnel. For overseas customers, please contact the official website for after-sales service.

Product daily problems

1. When plugged in the battery, the aircraft does not pass the self-test without "BBB" sound. There is only one sound.

Please check if the ESC agreement is correct

2. The spin of the aircraft keeps spinning

1. Please check if the propeller is correct
2. Please check if the motor direction is correct