

1. Turn off the device, unplug the power cord, and use a hexagonal wrench to remove the two screws that secure the power supply. Remove power.
2. Install the coupling (④) on the stepper motor (①) and tighten the screws. Fix the motor on the aluminum profile using hexagonal screws and motor fixing base (⑦).



3. Remove all the pulley fixing screws on the right side of the X-axis.
4. Use long screws to fix the Ztt sheet metal (⑤), and install it on the sheet metal on the right side of the X axis. Screw the T8 screw rod (⑧) into the screw nut to the coupling, and tighten the coupling screw.
5. Install the one for two motor cables (⑥) to the main board, and connect two Z motors.
6. Install the Phillips screw and boat nut on the power supply holder (③), and install the power supply.
7. Place the two screw fixing seats (②) on the left and right sides of the X-axis aluminum profile, and let the Z-axis rise to the highest position. If one side is uneven, turn the corresponding coupling clockwise.
8. Install the Z-axis screw fixing seat (②), and tighten the screws. Pay attention to the alignment position of the fixing seat.
9. If any Z axis does not run smoothly during operation, please try to loosen the screw corresponding to the Z axis in the circle on the right. If the right pulley is too loose, adjust the eccentric bolt in the box.

