





## Tools needed and spare parts list



1.Install the camera to the mount holder with M1.2x5, you can put some hot melt glue to fixed the camera



2.Install the camera and mount holder to the canopy with M1.3x4 screws



3.Install the motors to the frame with M1.4x3 screws



4.Motor directioan

## *LIRLIAVF*



5.Make M2x10 screws through the frame, and then use M2 nylon nuts to  $\hat{\mathbf{n}} \mathbf{x}$ 



7.Insert the wire plug of the camera to the socket of the flight controller and then use M2 Nylon nut to fixed the canopy

## URUAV UZ80 Kit assemble tutorial



6.Put the rubber damping ball on the M2x10 screw to install the flight controller



8.Insert the wire plug of the motor to the flight controller



## **Bind procedure**

UZ80 Frsky version bind procedure:

(Receiver mode "Frsky\_D" and choose "Frsky D8" for your radio transmitter)

Plug USB and then press the bind button for 1 second ,the Red LED on the top of the

flight controller will getting to be solid , this indicate the receiver is

in bind mode. Or Plug USB and then connect betaflight configurator. Go to CLI command then enter "frsky\_bind", the receiver would get into bind mode too. Make your Frsky transmitter get into bind mode . If bind is successful the red LED will starting to blink. The red LED wouldn't blinking when binding with some new ACCESS firmware frsky radio, but the bind is actual successful, need to go to CLI command and enter "save" to finish the binding. UZ80 Flysky version bind procedure:

(Receiver mode "A7105\_FLYSKY\_2A" and choose

"AFHD\$2A" for your radio transmitter

Press and hold the bind button for 1 second ,then plug

USB, the Red LED at the bottom of the flight controller will blinking

fast , this indicate the receiver is in bind mode. Make your Flysky transmitter get into bind mode . If bind is successful the red led will getting to be solid.