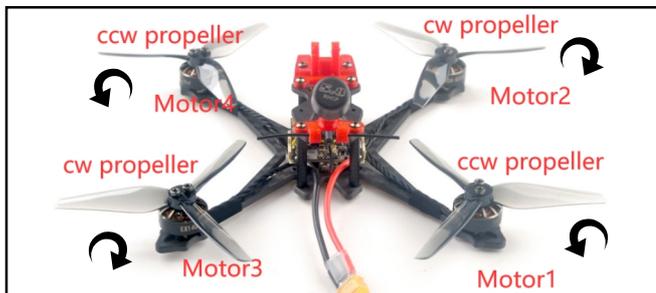


Features	
Ultra-lightweight 3.5-inch BNF FPV Freestyle Drone	
HD video transmission and analog video transmission are optional	
Integrated ExpressLRS SPI receiver or Frsky SPI D8/D16 receiver	
High efficiency EX1404 power system	
Can be equipped with Naked Gopro or SMO4K	
Support 3-4S battery 4S 750mah battery is recommended, maximum support 4S 1100mah	
Specifications	
Brand: Happymodel	
Product name: Crux35/Crux35 HD	
Wheelbase: 150mm	
Weight: Crux35 87gram/Crux35 HD 108gram	
Size: 130mmx130mmx45mm(without propellers)	
Receiver option: SPI ExpressLRS 2.4GHz/SPI Frsky D8/D16 (S-FHSS compatible)	
Camera option: HD version Nebula+Vista/Analog version Ant+OVX303 VTX	
Flying time: 9min~15min 4s 750mah battery	

Package Includes		
Item Name	Crux35	Crux35 HD
Crux35 Frame	1	1
Option1: ELRS X1 flight controller		
Option2: CrazyF411 flight controller	1	1
CaddxFPV Digital HD Camera Nebula Nano Kit	0	1
Analog FPV Camera Caddx Ant	1	0
Happymodel OVX303 5.8G analog VTX	1	0
Happymodel EX1404 KV3500 brushless motor	4	4
HQProp T3.5X2X3Grey (4cw+4ccw)	1	1
Screw Driver	1	1
Buckle Velcro for battery	1	1

1. Install propeller and mount the antenna holder

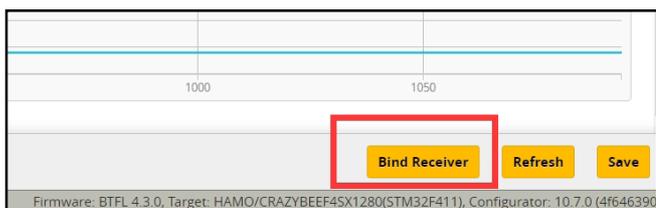
Default Propeller installation of Crux35 was set to be "Prop Out", please install CCW propeller to Motor1 and Motor4 and install CW propeller to Motor2 and Motor3, make sure you have mounted the screws tightly for the propellers.



2. Bind procedure

Please make sure that the Opentx version of your radio transmitter has been upgraded to 2.3.1 or latest and also the ELRS TX module firmware version has been upgraded to 1.0.0 or 1.0.1 before you starting to bind with the Crux35 ELRS version.

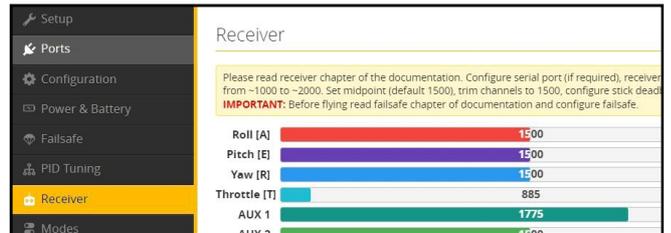
1) Power the flight controller by connecting USB. And open Betaflight Configurator (Latest version) to connect, enter to the "receiver" interface, and then click "Bind Receiver", the red LED at the bottom of the flight controller will flash quickly which means that the SPI ELRS receiver enters the bind mode. There is another way to make the receiver enter the bind mode: after connecting to the Betaflight configurator, move to the CLI interface and enter "bind_rx" in the command line.



2) After correctly connecting the ELRS 2.4GHz Tx module to your Opentx radio transmitter, copy the latest version of ELRS.LUA file to the SD card in the remote controller. The directory is "SD Card/Scripts/tools". Then run ELRS.LUA and set Pkt.Rate to "250Hz" to match with the flight controller. Then click "bind" to bind with the SPI ExpressLRS receiver. After binding is successful, the Red LED at the bottom of the flight controller will get to be solid.



3) Check the receiver channel map and channel value is correct after bind successful.



If the channel value is abnormal after bind successful, you can enter the following command in CLI

```
set expresslrs_hybrid_switches = ON
save
```

Noticed: The Pkt.Rate was set to "250Hz" for the Crux35 ELRS version out of factory. Only the same Pkt.Rate between the radio and the SPI receiver could link together. You can also change it from the CLI Command by the following command. Set expresslrs_rate_index = 1

```
Allowed range: 0 - 4
Default value: 0
0=500Hz,1=250Hz,2=150Hz,3=50Hz,4=25Hz
```

3. Arm/Disarm the Motor

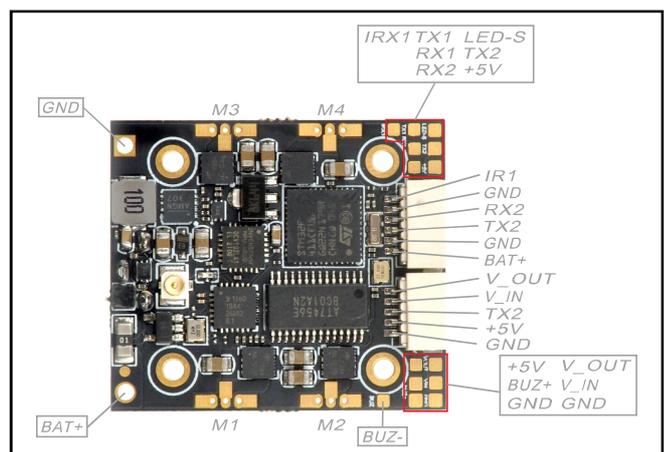
1) Turn on your radio transmitter and connect the battery to the Crux35. Then place Crux35 horizontally on the ground. We recommend 4S 750mah or 4S 850mah Li-po battery for Crux35 and Crux35 HD
2) Prepare your goggles, and match the channel with the VTX_table

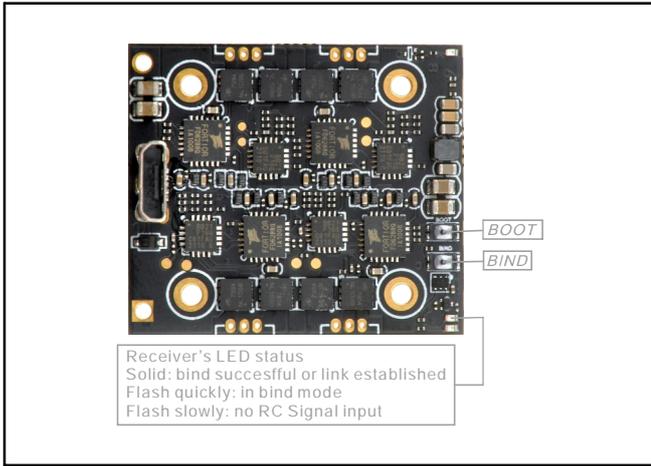
VTX Table											
Number of bands		Number of channels by band									
Name	Letter	Factory	1	2	3	4	5	6	7	8	
BOSCAM_A	A	5865	5845	5825	5805	5785	5765	5745	5725		Band 1
BOSCAM_B	B	5733	5752	5771	5790	5809	5828	5847	5866		Band 2
BOSCAM_E	E	5705	5685	5665	5645	5625	5605	5585	5565		Band 3
FATSHARK	F	5740	5760	5780	5800	5820	5840	5860	5880		Band 4
RACEBAND	R	5658	5695	5732	5769	5806	5843	5880	5917		Band 5
LOWRACE	L	5333	5373	5413	5453	5493	5533	5573	5613		Band 6

Number of power levels					
1	2	3	4	5	Value
1	2	14	20	26	
0	RCE	25	100	400	Label

3) Toggle Aux1 switch to arm the motors, the Green LED at the bottom of the flight controller would get to be solid once armed, happy flying.

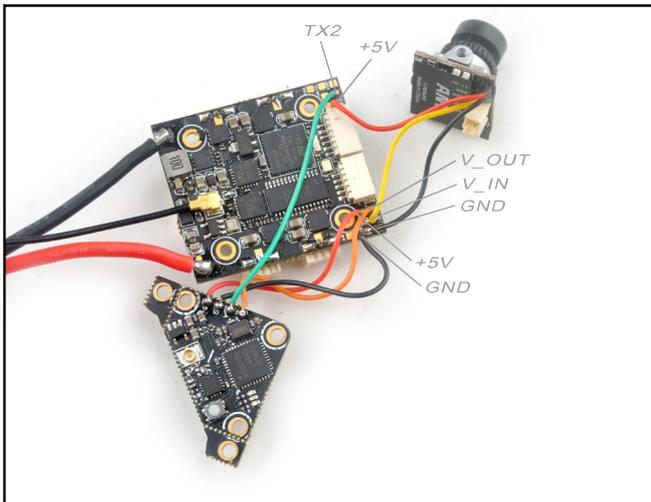
4. Flight controller connection diagram



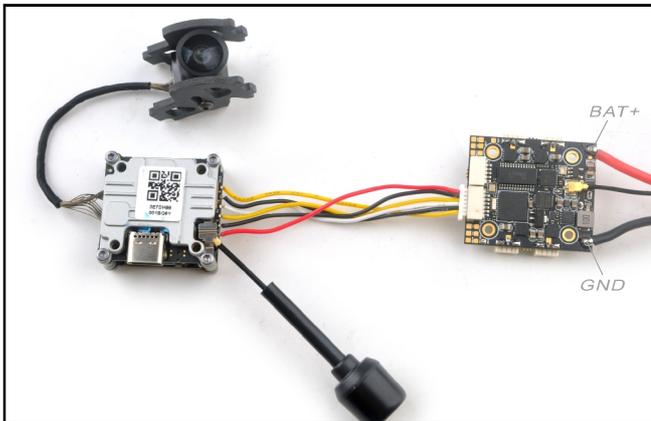


5. Electronic hardware connection diagram

Analog version



HD version



6. Some settings of Betaflight configurator

Analog version

Identifier	Configurations/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	<input type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	VTX (TBS Sms) AUTO

HD version

Identifier	Configurations/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	<input checked="" type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO

If you want to work with DJI Radio, please setting like the following steps

Identifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	<input checked="" type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART1	<input type="checkbox"/> 115200	<input checked="" type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO
UART2	<input checked="" type="checkbox"/> 115200	<input type="checkbox"/>	Disabled AUTO	Disabled AUTO	Disabled AUTO

Receiver

Serial-based receiver (SPEKSAT, €) Receiver Mode

Note: Remember to configure a Serial Port (via Ports tab) and choose a Serial Receiver Provider when using RX_SERIAL feature.

SBUS Serial Receiver Provider

Voltage and Currents meter settings

Voltage Meter

Battery 0.6 V

Scale: 110

Divider Value: 10

Multiplier Value: 1

Amperage Meter

Battery 0.00 A

Scale [1/10th mA]: 470

Offset [mA]: 0

ExpressLRS settings in the CLI

```
# set expresslrs
expresslrs_uid
Array length: 6
Default value: 0, 0, 0, 0, 0, 0

expresslrs_domain = ISM2400
Allowed values: AU433, AU915, EU433, EU868, FCC915, ISM2400
Default value: AU433

expresslrs_rate_index = 1
Allowed range: 0 - 4
Default value: 0

expresslrs_hybrid_switches = ON
Allowed values: OFF, ON
Default value: OFF
```

7. Analog version VTX Bands and Channels setup

Frequency and channel frequency table:

FR \ CH	CH1	CH2	CH3	CH4	CH5	CH6	CH7	CH8
BOSCAM_A	5865M	5845M	5825M	5805M	5785M	5765M	5745M	5725M
BOSCAM_B	5733M	5752M	5771M	5790M	5809M	5828M	5847M	5866M
BOSCAM_E	5705M	5685M	5665M	5645M	5885M	5905M	5925M	5945M
FATSHARK	5740M	5760M	5780M	5800M	5820M	5840M	5860M	5880M
RACEBAND	5658M	5695M	5732M	5769M	5806M	5843M	5880M	5917M
LOWRACE	5333M	5373M	5413M	5453M	5493M	5533M	5573M	5613M

There are 2 ways to switch the vtx channels:

- 1.If we need to use Channel 5705 then we should Go to Betaflight CLI,type the command:
Set VTX_band=3
Set VTX_channel=1
save
- 2.Disarm the Crux35 and then move the stick of the transmitter (THR MID+YAW LEFT+PITCH UP)to enter OSD Menu,Enter to Features,then enter to VTX SA to set VTX Band and channel

