

Features	
AIO 4IN1 Crazybee F4 Lite flight controller built-in 5.8G VTX	
Extreme light 1\$ 65mm Brushless whoop only 20g	
Runcam Nano3 The lightest 1/3 CMOS 800TVL Camera	
Smooth and powerful	
Compatible for 1S Lipo/LIHV	
Camera Angle adjustable	
Specifications	
Brand Name: Happymodel	
Item Name: Mobula6 1S 65mm Brushless whoop drone BNF version	
Wheelbase: 65mm	
Size: 80mm*80mm*37mm	
Weight: 20g	
Receiver option:	
Internal SPI Frsky version (Compatible with ACCST D8/D16, Recommend D8 mode)	
Internal SPI Flysky version(Compatible with AFHDS and AFHDS-2A Flysky transmitter)	
Internal SPI ELRS 2.4Ghz version(Compatible with ExpressLRS V2.0 or latest TX module)	
Motor speed option:	
SE0802 KV25000(Race Edition)	
SE0802 KV19000(Regular Edition)	

### Package includes

Item Name	Qty
Mobula6 1S 65mm whoop Drone Frame	1
SPI Receiver Option1: Crazybee F4 Lite FC built-in Frsky SPI D8 RX	
SPI Receiver Option2: Crazybee F4 Lite FC built-in Flysky SPI RX	1
SPI Receiver Option3: ELRSF4 2G4 V3.1 FC built-in ELRS 2.4Ghz v2.0 SPI RX	
SE0802 KV19000 or KV25000 brushless motor	4
Gemfan 1219-3 Propellers(4cw+4ccw)	1
Runcam Nano3 1/3 CMOS 800TVL camera	1
5.8G 0-400mw 48ch onboard Openvtx	4
1\$ 300mah 30C LiHV Battery	1
1S Lipo/LIHV USB Charger	1
Propeller disassemble tool	1

## Flight controller connection diagram





#### Binding procedure

 Powering the Mobula6 first, then Press the bind button for 1 second , the red Led at the bottom of the flight controller will blinking fast, this indicate the receiver is in bind mode.



Another simple way to get into Bind mode :

Plug the USB and go to the CLI command tab from Betaflight configurator then type "bind\_rx" or Go to Receiver tab from Betaflight configurator then hit "Bind Receiver",

the red LED will getting to be solid ,and it means the receiver is in bind mode.



3.Make your Flysky transmitter to bind mode, the LED at the bottom of the flight controller will getting to be solid if bind successfully. The Default SPI receiver protocol is AFHDS2A, so please check your radio transmitter is matched.



#### Receiver configuration

Please set Receiver mode to be SPI RX Support from the Configuration tab of the Betaflight Configurator, then select A7105\_Flysky\_2A Provider for AFHDS-2A Protocol Radio transmitter or Select A7105\_Flysky Provider for AFHDS Protocol Radio transmitter, don't enable Serial RX since the Crazybee F4 lite Flight controller is integrated SPI BUS Receiver

luentifier	Configuration/MSP	Serial Rx	Telemetry Output	Sensor Input	Peripherals
USB VCP	115200 🔻		Disabled • AUTO •	Disabled • AUTO •	Disabled • AUTO •
UART1	115200 •		Disabled • AUTO •	Disabled • AUTO •	Disabled • AUTO •
UART2	115200 •		Disabled • AUTO •	Disabled • AUTO •	TBS SmartAuc • AUTO •
Receive	er				
SPI R)	( support		Receiver Mode		
Note:	The SPI RX provider	will only w	ork if the required hard	vare is on board or conr	ected to an SPI bus.
A7105	_FLYSKY_2A		• Flysky A	FHDS-2A	
Receive	er				
Receive SPI R	er K support		Receiver Mode		
Receive SPI R) Note:	er K support The SPI RX provider	will only w	Receiver Mode  vork if the required hardv	vare is on board or conn	ected to an SPI bus.

### Arm/Disarm the Motor

1. The Default Arm/Disarm switch for Mobula6 is AUX1(Channel 5),and you can also customize it with Betaflight Configurator.

Nodes																				WIKI
Use ranges to di activate the moi	efine the switch de. Remember t	es on yo o save y	ur transi our setti	nitter i ngs usi	and cor ng the	respon Save bu	ling m tton.	ode as	signmer	nts. A re	ceive	r chani	nel tha	t give	s a read	ting b	etwee	in a range	min/max	will
ARM	AUX 1 V		1.01						P	- 1		1			1			·		0
Add Range	Max: 2100	900	1000			1200			1400	1500	)	1600			1800			2000	2100	
AIR MODE Add Range																				
ANGLE	AUX 2 🔻																			0
Add Range	Min: 1200 Max: 2100	 900	1000			 1200			 1400	1500	5	 1600			 1800			2000	2100	

2. Set Arm/Disarm switch for your Flysky Radio: Move to the Aux.channels interface, Set "SWA" or "SWB" or "SWC" switch etc. for Ch5 to ARM/DISARM the motor.



3. The default channel map for Mobula6 Flysky version is AETR1234, please make sure your transmitter is matched, otherwise it will can't be armed. Toggle the AUX1 Switch, the Green LED on the flight controller will getting to be solid, this indicates the Mobula6 was armed. And also you can found "Armed" displayed on your FPV Goggles or the FPV Monitor. Please make sure keep the Mobula6 level before arming. Be careful and enjoy your flight now!



6 \$ Nu	imbe	r of ba	ands	8 ‡	N	umber	of	hanne	ls b	y band										G
Name	L	etter l	Factory	1		2		3		4	5		6		7		8			6
BOSCAM	A	A		5865	\$	5845	-	5825	-	5805	\$ 5785	\$	5765	-	5745	-	5725	-	Band 1	
BOSCAM	в	в		5733	\$	5752	\$	5771	\$	5790	\$ 5809	\$	5828	\$	5847	\$	5866	\$	Band 2	
BOSCAM	Е	E		5705	-	5685	\$	5665	\$	5645	\$ 5885	-	5905	\$	5925	-	5945	*	Band 3	
FATSHAR	ĸ	F		5740	\$	5760	\$	5780	\$	5800	\$ 5820	\$	5840	\$	5860	\$	5880	\$	Band 4	
RACEBAN	ID	R		5658	\$	5695	-	5732	-	5769	\$ 5806	\$	5843	-	5880	\$	5917	-	Band 5	
LOWRAC		L		5333	\$	5373	\$	5413	\$	5453	\$ 5493	\$	5533	\$	5573	\$	5613	\$	Band 6	
5 \$ N	imbe	r of po	ower lev	rels																6
1		2	3		4			5												6
10 🗘	2	\$	14	\$	20	\$	26	\$	Valu	le										
0	RCE	E	25	Ĩ	100		400		Lab	el										

There are 2 ways to switch the vtx channels:

1.If we need to use Channel 5769 then we should Go to Betaflight CLI, type the command:

Set VTX\_band=5

Set VTX\_channel=4

save

2.Disarm the Mobul6 and then move the stick of the transmitter(THR MID+YAW LEFT+PITCH UP)to enter OSD Menu,Enter to Features,then enter to VTX SA to set VTX Band and channel



Mixer type and ESC/motor protocol



## Default PID settings for Betaflight 4.3.0



### ESC Check and Flash firmware 1.Download New release Bihelisuite from: <u>https://www.mediafire.com/folder/dx6kfaasyo24I/BLHeliSuite</u> 2.Plug the usb and connect the flight controller to computer



3.Open the Device Manager of your computer, find the Ports, please make sure the Com port Serial Number is under 255, otherwise it will can't connect to the BLHELISUITE. You can change the port serial number like the bellowing step :

Recycle Bin         B: ● Monitors           Recycle Bin         E: ● Monitors           B: ● Monitors         E: ● Monitors           B: ● Universal Serial Bus controllers         E: ● Universal Serial Bus controllers	STEdenoslectranics Webpal COH Port (COHGSD) Properties:
divenced Settings for C014336  Use FirD buffers (equires 15550 compatible UART)  Select lower retings to correct connection problems.  Select higher settings for faster performance.	Party, Hone Party, Party, Hone Party,
Beolive Buffer: Low (1)	Hgh (14) (14)
COM Port Number: COM256	OK Cancel

4.Open the BLHELISUITE, Select SILABS BLHeli Bootloader (Cleanflight) from the third tab on the top side. Then Select the right Serial com port and Click connect. You can also Flash the new release BLHeli\_s firmware via the BLHEILISUITE, the firmware Target is "O-H-05"

BLHeliSuite 16.7.	14.9.0.1 [m4	wFCIntf SiL	abs-BLB @COM3	]		-		×
ES <u>C</u> setup ESC <u>t</u> oo	ls S <u>e</u> lect A	TMEL / SIL	ABS Interface	Options ? <u>B</u> LH	leliinfo <u>S</u> ave S	creenshot		
SiLabs ESC Setup	ESC over	view	Motors	Make interface	25			
ESC# 1 - Name		O-H-O5 for Mult BLHei_S	Firmware ta ticopter Moto Revision: 16.	rget Misc rs 80				
Startup Power 1.00 <	> ®	Motor Di	Normal >	PPM Min T	hrottle 1148	Startup Beep V 40 40 40	olume >	
Temperature Prote	ection >	Demag Co	Low >	PPM Max 1	Throttle 1832	Beacon/Signal V 80 80 80	/olume >	
Low RPM Power P	rotect	Motor Tir	ning Medium >	PPM Cente	er Throttle 1488	Beacon Delay	utes >	
		Flas	h firmware	Brake On S	Off >	Click check to se details of the 4in	e the 1 ESC	
Read Setup	🔒 Write	Setup	Flash BLHeli	😚 Flash Other				
Port: COM 3 🗸 Bau	d: 115200 、	🗸 📜 🕅	connect 1	ple ESC / Master	#1	db Check		
Found Multiple ESC: E	SC#1 ;ESC#	2 ;ESC#3 ;E	SC#4 ;					

Flight controller firmware update

1.Install latest STM32 Virtual COM Port Driver

http://www.st.com/web/en/catalog/tools/PF257938

2.Install STM BOOTLOAD Driver (STM Device in DFU MODE)

3.Open Betaflight configurator and choose firmware target "Crazybee F4 FS(Legacy)", then select the firmware version.

4.There are 2 ways to get in DFU Mode: 1). solder the boot pad and then plug USB to computer 2). loading betaflight firmware and hit "flash", then it will getting into DFU Mode automatically. 5.Open Zadig tools to replace the drivers from STM32 Bootloader to WINUSB Driver.

6.Reconnect the flight controller to the computer after replace driver done , and open Betaflight Configurator, loading firmware and flash.

CTM22	BOOTLOADED		
51M32	BOUTLOADER		•
Driver	STTub30 (v3.0.4.0)	📫 WinUSB (v6. 1. 7600. 16385)	More Information WinUS8 (libusb)
USB ID	0483 DF11		ibusb-win32
wcm2	×	Replace Driver	IbusbK

# "Flip over after crash" procedure

Set one channel of your radio transmitter to activate the Flip over function in the Mode tab of Betaflight configurator.

The default Switch for Activate "Flip" is AUX4(Channel8)

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CRASH Add Link Add Range	AUX 4 V Min: 1300 Max: 2100	900	' 1000	1 1	1200	'   ' 1400 -	₿ <sup>1</sup>   <sup>1</sup> 1500 1600	'   1800	''''  2000	2100